

Bayesian Online Changepoint Detection

Adams & MacKay, 2007

Elijah Whitham-Powell

The Problem

Financial time series exhibit *regime changes*

We want to detect them **online, as they happen**

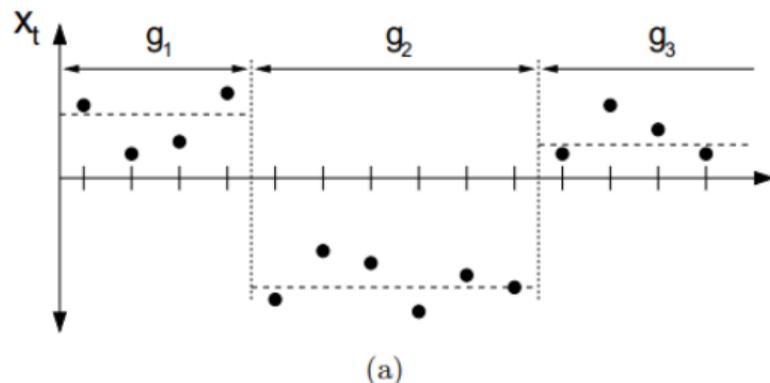
A Bayesian Approach

MMD: nonparametric, retrospective

BOCPD: parametric likelihood, maintains a **posterior over changepoint locations**

Problem Setup

- ▶ Data divided into non-overlapping segments
- ▶ Within each segment: i.i.d. with segment-specific parameters
- ▶ Boundaries between segments are **changepoints**
- ▶ New segments get fresh parameters from the prior

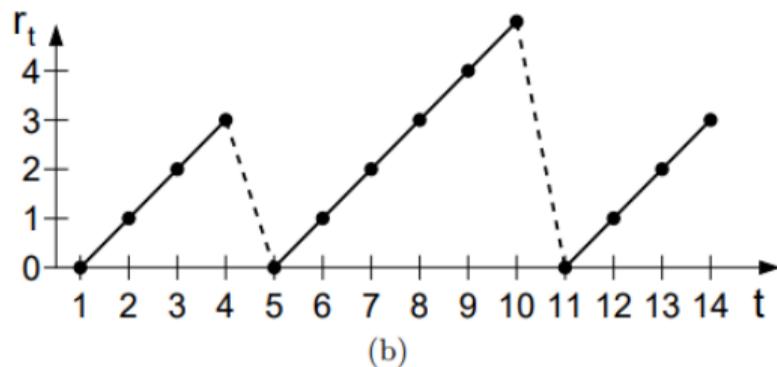


Run Length

The **run length** r_t counts time steps since the last changepoint.

At each step, only two outcomes:

1. Run **continues**: $r_t = r_{t-1} + 1$
2. **Changepoint**: $r_t = 0$



Resets to zero at each changepoint, then climbs linearly.

The Hazard Function

“Given that the current regime has lasted τ steps, what is the probability it ends now?”

$$H(\tau) = \frac{P_{\text{gap}}(g = \tau)}{\sum_{t=\tau}^{\infty} P_{\text{gap}}(g = t)}$$

This determines the **changepoint prior**:

$$P(r_t | r_{t-1}) = \begin{cases} H(r_{t-1} + 1) & \text{if } r_t = 0 \\ 1 - H(r_{t-1} + 1) & \text{if } r_t = r_{t-1} + 1 \end{cases}$$

Constant hazard (memoryless)

$$P_{\text{gap}} \sim \text{Geometric}(\lambda) \Rightarrow H(\tau) = \frac{1}{\lambda} \quad \forall \tau$$

A modeling choice

Algorithm is fully general — any P_{gap} works. λ controls expected time between changepoints.

The Core Idea: Marginal Prediction

$$P(x_{t+1} | x_{1:t}) = \sum_{r_t} P(x_{t+1} | r_t, \mathbf{x}_t^{(r)}) P(r_t | x_{1:t})$$

Predictive distribution

$$P(x_{t+1} | r_t, \mathbf{x}_t^{(r)})$$

“If the current regime has lasted r_t steps, what do I expect next?”

Run length posterior $P(r_t | x_{1:t})$

“How likely is each possible run length given everything observed?”

The Recursive Update

$$P(r_t, x_{1:t}) = \sum_{r_{t-1}} \underbrace{P(r_t | r_{t-1})}_{\text{CP prior}} \underbrace{P(x_t | r_{t-1}, \mathbf{x}_t^{(r)})}_{\text{predictive likelihood}} \underbrace{P(r_{t-1}, x_{1:t-1})}_{\text{previous step}}$$

Changepoint prior

Did the run continue or end?

Predictive likelihood

How well did this model predict?

Previous time step

Already computed — recursion!

Why conjugate priors?

Need to update beliefs about segment parameters at every time step.

Conjugate priors allow this via **sufficient statistics** — a running tally rather than storing raw data.

Sufficient statistics update

$$\nu_t^{(r)} = \nu_{\text{prior}} + r_t$$

$$\chi_t^{(r)} = \chi_{\text{prior}} + \sum_{t' \in r_t} u(x_{t'})$$

ν counts observations; χ accumulates statistics.

Algorithm 1: The Full Procedure

1. **Initialize**

$$P(r_0=0) = 1$$

$$\nu_1^{(0)} = \nu_{\text{prior}}, \quad \chi_1^{(0)} = \chi_{\text{prior}}$$

2. **Observe datum x_t**

3. **Evaluate predictive probability**

$$\pi_t^{(r)} = P(x_t | \nu_t^{(r)}, \chi_t^{(r)})$$

4. **Calculate growth probabilities**

$$\begin{aligned} P(r_t = r_{t-1} + 1, x_{1:t}) \\ = P(r_{t-1}, x_{1:t-1}) \pi_t^{(r)} (1 - H(r_{t-1})) \end{aligned}$$

5. **Calculate changepoint probabilities**

$$\begin{aligned} P(r_t = 0, x_{1:t}) \\ = \sum_{r_{t-1}} P(r_{t-1}, x_{1:t-1}) \pi_t^{(r)} H(r_{t-1}) \end{aligned}$$

6. **Calculate evidence**

$$P(x_{1:t}) = \sum_{r_t} P(r_t, x_{1:t})$$

7. **Determine run length distribution**

$$P(r_t | x_{1:t}) = P(r_t, x_{1:t}) / P(x_{1:t})$$

8. **Update sufficient statistics**

$$\nu_{t+1}^{(0)} = \nu_{\text{prior}}, \quad \chi_{t+1}^{(0)} = \chi_{\text{prior}}$$

$$\nu_{t+1}^{(r+1)} = \nu_t^{(r)} + 1$$

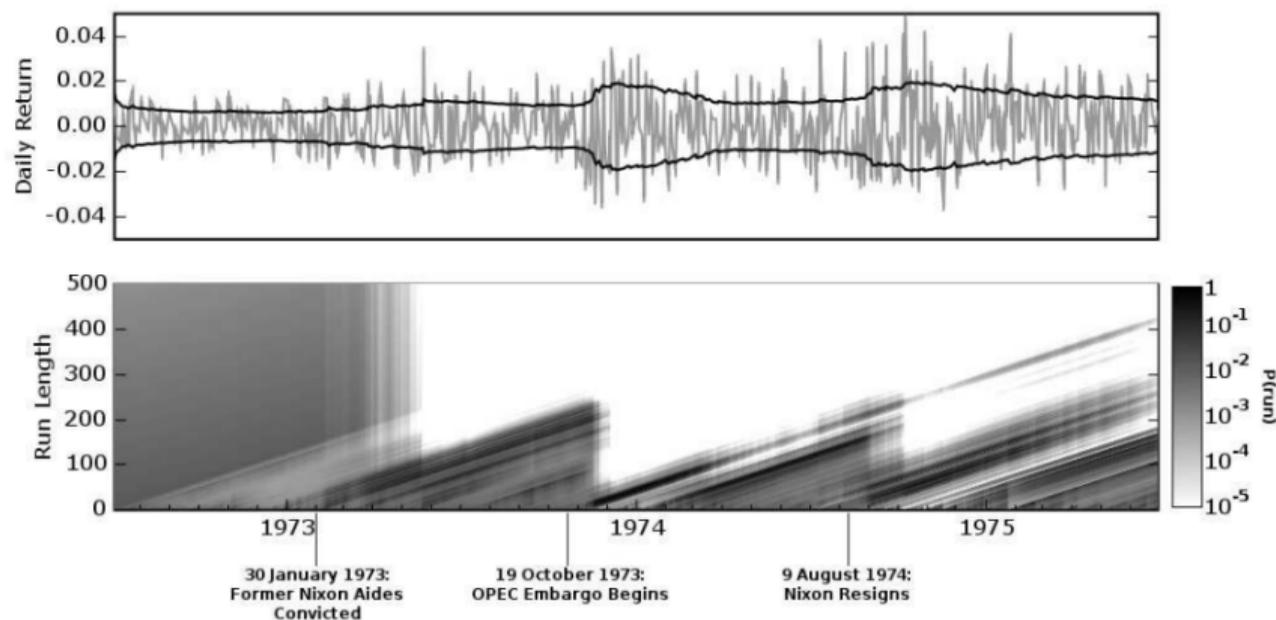
$$\chi_{t+1}^{(r+1)} = \chi_t^{(r)} + u(x_t)$$

9. **Perform prediction**

$$\begin{aligned} P(x_{t+1} | x_{1:t}) \\ = \sum_{r_t} P(x_{t+1} | r_t, \mathbf{x}_t^{(r)}) P(r_t | x_{1:t}) \end{aligned}$$

10. **Return to step 2**

Application: Dow Jones 1972–75



Top: daily returns with predictive volatility. Bottom: posterior $P(r_t | x_{1:t})$ — the “staircase” shows growing runs; drops to zero indicate changepoints.

Next Steps: Regime Detection

I will implement BOCPD for market regime detection and compare with my existing MMD-based approach.

Online vs. Retrospective

BOCPD processes one point at a time; MMD compares windows after the fact

Parametric vs. Nonparametric

BOCPD assumes a distributional model; MMD detects any distributional shift

Posterior vs. Permutation Test

BOCPD gives a full distribution over changepoints; MMD uses p-values

Adams, R. P. & MacKay, D. J. C. (2007). Bayesian Online Changepoint Detection. arXiv:0710.3742

References

Adams, R. P. & MacKay, D. J. C. (2007). Bayesian Online Changepoint Detection.

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